



1·2·3 FÉVRIER 2023

MARSEILLE·PALAIS DU PHARO



6 minutes pour convaincre

L'angioplastie robotisée

Eric Durand

CHU de Rouen

INSERM U1096

FHU CARNAVAL

Liens d'intérêt



- Robocath, Edwards Lifesciences: consultant

1. Parce que pas grand-chose n'a changé ?



- ✓ **Des progrès majeurs en angioplastie** coronaire depuis 1977:
 - Utilisation de la voie radiale
 - Amélioration des dispositifs (sonde, guide, ballon, stent,...)
 - Optimisation de la pharmacothérapie
 - Amélioration de l'évaluation des lésions (FFR, IVUS, OCT)

- ✓ **Peu d'évolution des aspects pratiques de l'angioplastie par l'opérateur** (manipulation des guides, des ballons et des stents sous Rx)

1. Parce que la robotique occupe une place croissante en médecine !

UROLOGIE/GYNÉCOLOGIE



1999

DA VINCI
Intuitive Surgical



2016

ALF-X
Transenterix

NEURO



2008
NEUROMATE
Renishaw



2008
ROBODOC
Think Surgical

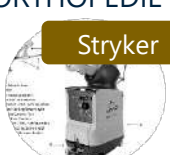


2011

ROSA
Medtech

Zimmer

ORTHOPÉDIE



2006

RIO
Mako Surgical

Stryker



2011

RENAISSANCE
Mazor robotics

Medtronic

CARDIOLOGIE INTERVENTIONNELLE



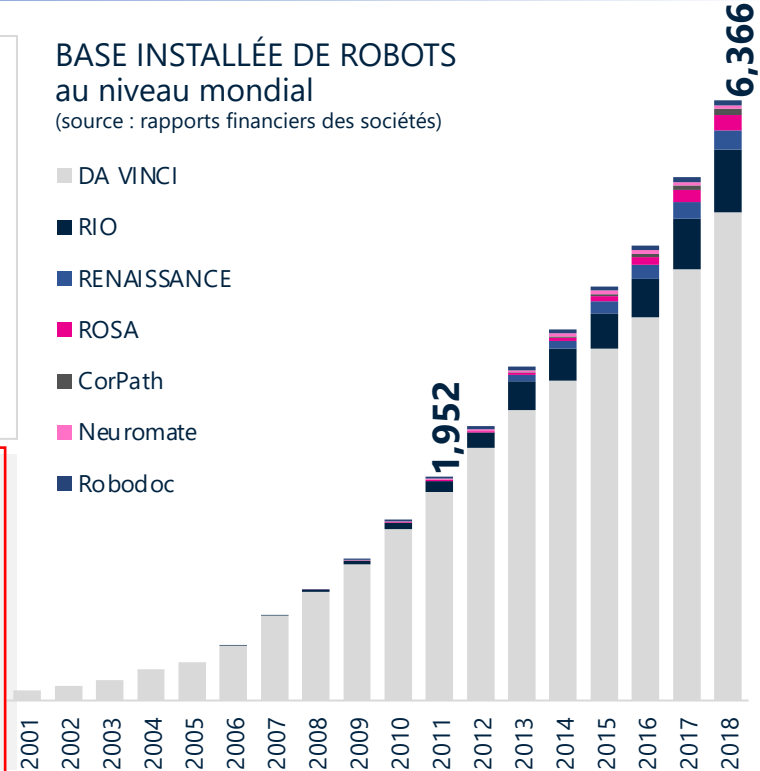
2011
Corpath GRX
Corindus

Siemens



2019
R-One™
Robocath

BASE INSTALLÉE DE ROBOTS
au niveau mondial
(source : rapports financiers des sociétés)



1. Deux plateformes robotiques actuellement disponibles sur le marché européen

CorPath 200 et CorPath GRX
Corindus/Siemens Healthineers
US/Germany

R-One Robocath
Rouen, Normandie, France



Translation and rotation of the catheter and the guide



2. Car nous sommes exposés à des risques !

Hazards of Radiation Exposure	Hazards of Protection from Radiation Exposure	Other Hazards
1. Cancer <ul style="list-style-type: none">• Basal cell skin cancer• Chronic myelogenous leukemia• Thyroid cancer• Brain tumor	1. Orthopedic Injury <ul style="list-style-type: none">• Lumbosacral spine• Cervical spine• Hip• Knee• Ankle	Exposure to blood-borne infections
2. Cataracts	2. Operator Fatigue	
3. Effects on reproductive health <ul style="list-style-type: none">• Low sperm count• Teratogenesis	Am Heart J 2009;157:118-24	
4. Accelerated atherosclerosis		

Andreassi et al. JACC Cardiovasc Intv 2015

2. Car les autres alternatives sont insuffisantes ou peu adaptées à nos pratiques

Autres méthodes préventives d'exposition aux RX

Dose reduction (cathlab improvement)

- > **AlluraClarity** launched in 2012 by Philips is an interventional X-ray system that provides high quality imaging at low X-ray dose levels
- > **Artis Q.zen** launched in 2014 by Siemens also aims at reducing radiation dose

Apron improvement

- > **Zero Gravity** launched in 2010⁴⁾ by CFI Medical & Biotronik is a suspended body shield that provides following improvements:
 - increased radiation protection (protects all areas except hands)
 - increased comfort (suspended apron)

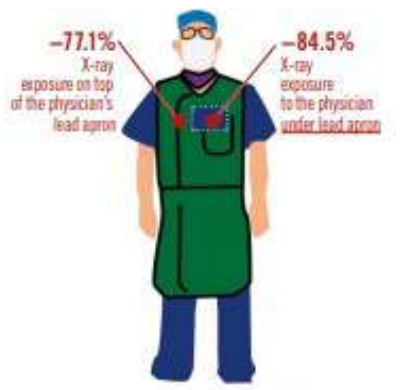
Apron emancipation

- > **CathPax** launched in 2012 by Lemer Pax is a mobile radio-protection cabin that allows:
 - increased radiation protection (protects all areas except hands)
 - total comfort (no apron, seated position)



3. Pourquoi intégrer la robotique vasculaire dans ma pratique quotidienne ?

1. Diminuer drastiquement mon exposition aux rayons X



5. Optimiser la procédure

- Point fixe permanent
- Avance millimétrique
- Torque robotique

4. Standardiser la procédure

- Courbe d'apprentissage rapide

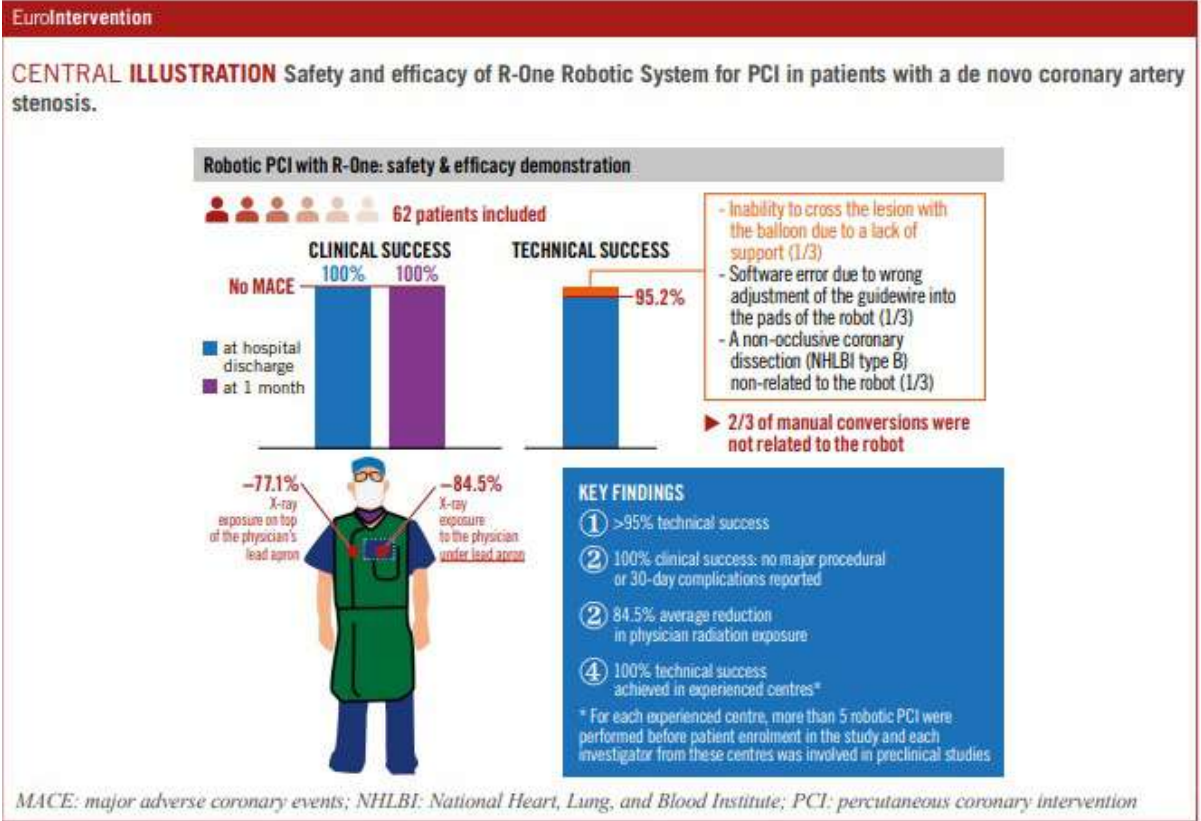
2. Réduire les troubles musculo-squelettiques



3. Améliorer l'ergonomie de travail

- Proximité visuelle des écrans
- Position assise

4. Pour quels résultats cliniques ?

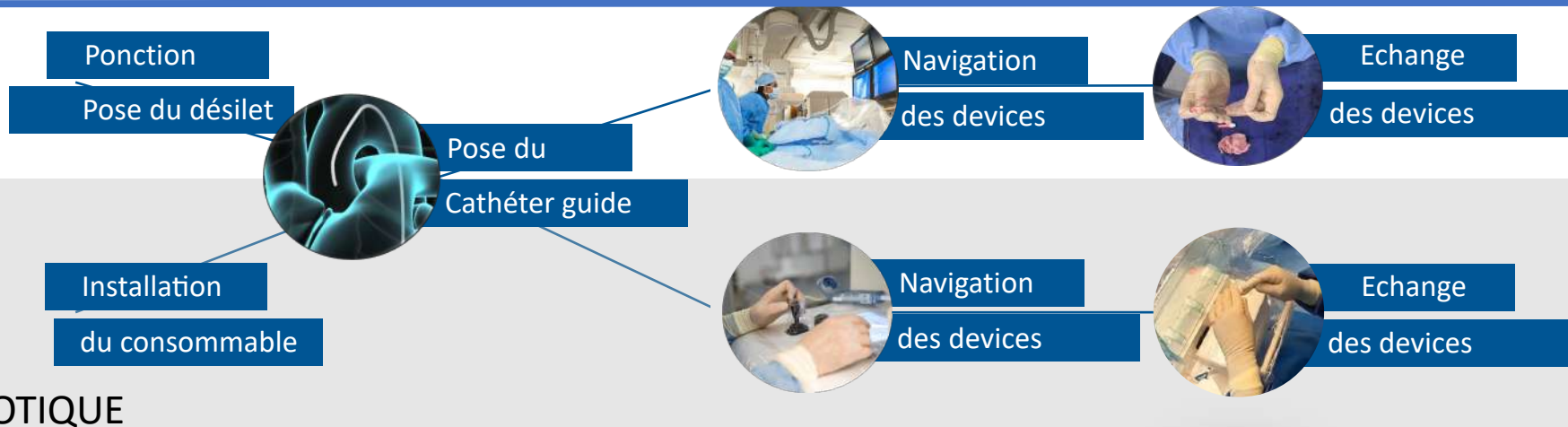


4. Pour quels résultats cliniques ?

	Beyar et al ²⁰	PRECISE ²¹	CORA-PCI ²²	Smitson et al ¹⁹	PRECISION Registry [*]	R-EVOLUTION
System used	RNS	CorPath 200	CorPath 200	CorPath GRX	CorPath GRX	R-One
Number of sites, n	1	9	n/r	1	20	6
Patients, n	18	164	108	40	980	62
Complex lesions, %	n/r	31.7	78.3	77.8	68.8	25.0
Technical success, %	83.3	98.8	91.7	90.0	86.5	95.2
Clinical success, %	100	97.6	99.1	97.5	97.8	100
MACE, % (follow-up)	0 (in-hospital)	0 (30 days)	0.9 (in-hospital)	n/r	0 (in-hospital)	0 (30 days)
Total procedure time, min	44	n/r	44.5	40.2	54.3	39.9
Total robotic procedure time, min	n/r	24.4	n/r	n/r	n/r	19.9
Mean fluoroscopy time, min	8.8	11.1	18.2	17.4	17.8	10.3
Mean contrast injection volume, mL	n/r	144.2	183.4	171	118.2	118.3
Mean patient radiation exposure, mGy	n/r	1,5	n/r	n/r	n/r	540.3
Mean reduction in operator radiation exposure with lead protection, %	n/r	n/r	n/r	n/r	n/r	84.5
Median reduction in operator radiation exposure, %	n/r	95.2	n/r	n/r	n/r	100 (under lead) 86.07 (on lead)

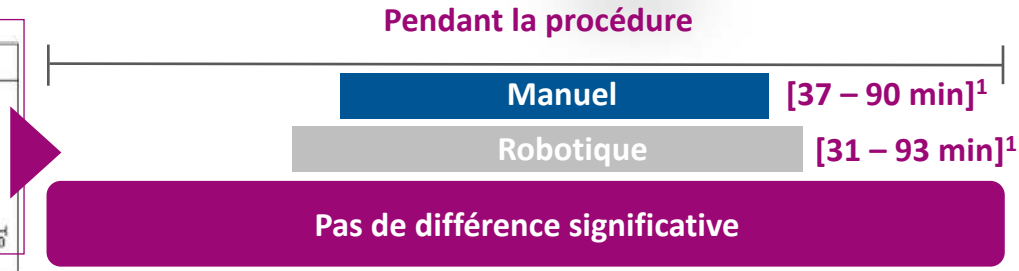
* (Medranda GA, Waksman R. Safety and Efficacy of the Second-Generation Robotic Assisted Systems for PCI. Society for Cardiovascular Angiography and Interventions. 2 July 2021; <https://scai.org/safety-and-efficacy-second-generation-robotic-assisted-systems-pci-coverage-late-breaking-science>. [Last accessed 7 Dec 2022]). MACE: major adverse cardiac event; mGy: milligray; n/r: not reported

5. Idée reçue n°1: une intervention robotique prend plus de temps qu'une intervention manuelle!



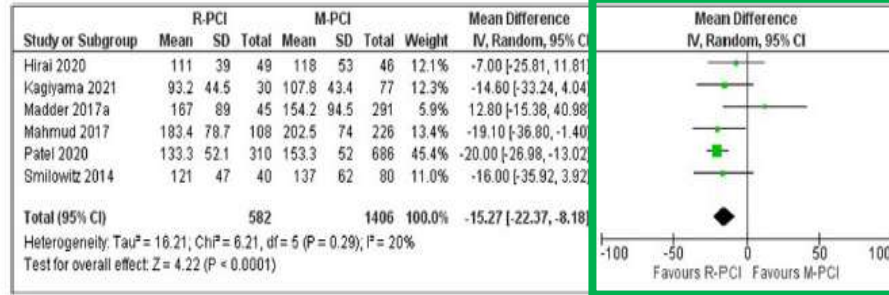
ROBOTIQUE

Study or Subgroup	R-PCI		M-PCI		Mean Difference		Mean Difference	
	Mean	SD	Total	Mean	SD	Total	Weight	IV, Random, 95% CI
Beyar 2006	44	32.7	10	61	19	20	5.7%	-17.00 [-34.26, 0.26]
Hirai 2020	89.6	27.1	49	93.4	30.5	46	10.7%	-3.80 [-15.43, 7.83]
Kagiyama 2021	72.4	41.2	30	85.6	34.8	77	6.1%	6.80 [-9.87, 23.47]
Madder 2017a	55	22	45	46.2	31.6	291	18.8%	8.80 [1.42, 16.18]
Mahmud 2017	44.5	26.1	108	36.6	23.1	226	23.5%	7.90 [2.13, 13.67]
Patel 2020	37	17.1	310	31.3	15.6	686	35.2%	5.70 [3.47, 7.93]
Total (95% CI)			560			1346	100.0%	4.55 [0.08, 9.02]
Heterogeneity: Tau ² = 13.46; Chi ² = 10.46, df = 5 (P = 0.06); I ² = 52%								
Test for overall effect: Z = 2.00 (P = 0.05)								



1 Jaffar-Karballai M, et al. J Cardiol. 2022 Feb 11:S0914-5087(22)00023-5. doi: 10.1016/j.jcc.2022.02.002. Epub ahead of print. PMID: 35165012.

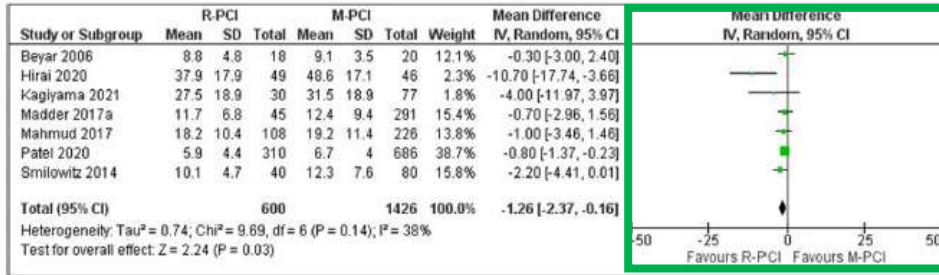
5. Idée reçue n°2 : il n'y a pas de bénéfice pour le patient !



Diminution du volume de contraste

Diminution de l'exposition aux Rx

Characteristics	T-PCI (n=280)	R-PCI (n=280)	P Value
AK, mGy	1110 (699-1498)	884 (537-1398)	0.002
Dose-area product, cGycm ²	5746 (3751-7833)	4734 (2695-7746)	0.003



Diminution de la durée de scopie

Jaffar-Karballai et al. J Cardiol 2022

5. Idée reçue n°3 : je ne peux pas traiter toutes les lésions

Table 6. Results comparison with similar devices.

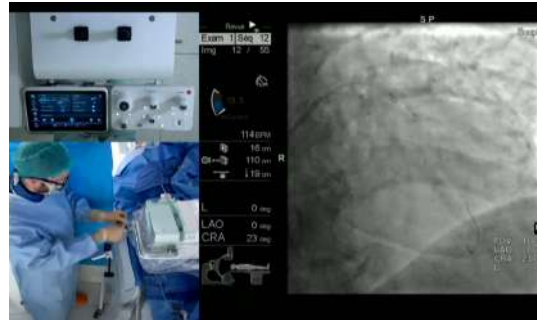
	Beyar et al ²⁹	PRECISE ²¹	CORA-PCI ²²	Smitson et al ¹⁹	PRECISION Registry [*]	R-EVOLUTION
System used	RNS	CorPath 200	CorPath 200	CorPath GRX	CorPath GRX	R-One
Number of sites, n	1	9	n/r	1	20	6
Patients, n	18	164	108	40	980	62
Complex lesions, %	n/r	31.7	78.3	77.8	68.8	25.0
Technical success, %	83.3	98.8	91.7	90.0	86.5	95.2
Clinical success, %	100	97.6	99.1	97.5	97.8	100
MACE, % (follow-up)	0 (in-hospital)	0 (30 days)	0.9 (in-hospital)	n/r	0 (in-hospital)	0 (30 days)
Total procedure time, min	44	n/r	44.5	40.2	54.3	39.9
Total robotic procedure time, min	n/r	24.4	n/r	n/r	n/r	19.9
Mean fluoroscopy time, min	8.8	11.1	18.2	17.4	17.8	10.3
Mean contrast injection volume, mL	n/r	144.2	183.4	171	118.2	118.3
Mean patient radiation exposure, mGy	n/r	1,5	n/r	n/r	n/r	540.3
Mean reduction in operator radiation exposure with lead protection, %	n/r	n/r	n/r	n/r	n/r	84.5
Median reduction in operator radiation exposure, %						100 (under

Hirai et al. 2020	Retrospective	CorPath GRX	95	Procedure time Cockpit time	46 Manual CTO-PCI 49 Robotic CTO-PCI	No difference in procedure time or MACE Higher cockpit time in robotic PCI	
-------------------	---------------	-------------	----	-----------------------------	---	---	--

5. Idée reçue n°4 : c'est l'opérateur secondaire/l'infirmier qui est désormais plus exposé

Exemple d'un cas enregistré en avril 2022
 > Mesure de doses sur les deux opérateurs
 (celui au robot et celui à l'unité de commande)

- Dose mesurée à l'unité de commande située en control room : **0 μ Sv**
- Dose mesurée au robot par l'opérateur en charge du chargement/déchargement des devices, inflation et injection de contraste) :
 - Sous le tablier plombé : **0,27 μ Sv**
 - Sur le tablier plombé : **0,47 μ Sv**



Successful introduction of robotic-assisted percutaneous coronary intervention system into Japanese clinical practice: a first-year survey at single center

Kotaro Kagiyama¹ · Yoshiaki Mitsutake¹ · Takafumi Ueno^{1,2} · Shinji Sakai¹ · Takuya Nakamura⁴ · Kazunori Yamaji¹ · Takashi Ishimatsu¹ · Masahiro Sasaki¹ · Hidetoshi Chibana¹ · Naoki Itaya¹ · Ken-ichiro Sasaki¹ · Yoshihiro Fukumoto¹

	R-PCI (p= 30)	M-PCI (p= 77)	p value
Clinical success* rate	93.3% (28)	92.2% (71)	0.97
Residual stenosis < 30%	93.3% (28)	92.2% (71)	0.97
In hospital MACE†	0%	0%	1.0
Robotic technical success‡ rate	90.0% (27)		
Completion robotically	83.3% (25)	–	–
Partial manual assistance	6.7% (2)		
Manual conversion	10.0% (3)		
Procedure time (min)	72.4 ± 41.2	65.6 ± 34.8	0.40
Fluoroscopy time (min)	27.5 ± 18.9	31.5 ± 18.9	0.33
Contrast medium (ml)	93.2 ± 44.5	107.8 ± 43.4	0.13
Radiation exposure			
Dose area product (Gyem ²)	77.6 ± 49.6	104.8 ± 54.4	0.02
To operator (μSv)	0 (0–1.3)	21.5 (12.0–37.5)	<0.0001
To assistant (μSv)	10.5 (8.8–20.3)	9.0 (4.0–15.0)	0.14

Pas de différence significative
 Manuel vs Robotique
 pour le second opérateur

6. Limites actuelles et prochains développements

Limites actuelles

- Impossibilité d'utiliser certains dispositifs (**OTW**, tels que : microcathéter, Rotablator), incompatibilité imagerie endovasculaire
- Impossibilité de mobiliser **simultanément** plusieurs guides et/ou ballons/stents
- **Perte du feed-back tactile**
- **Pas d'études randomisées** « manuel vs robotique »

Prochains développements

- **Registre** observatoire pour tous les centres impliqués dans un programme robotique
- **Intervention depuis la salle de contrôle**
- **Prochaine génération robotique:**
 - Repositionnement robotisé du cathéter guide
 - Management de plusieurs devices simultanément (rapid-exchange & over-the-wire)
 - Intégration complète dans le cathlab
- **Interventions à grande distance** (neuro ++ et pays manquant d'infrastructures en cardio) et **teleproctoring**
- **Digitalisation du cathlab** : collecte des données pour intégrations de mouvements semi-autonomes et autonomes à terme

6. En conclusion



Opérateurs

- **Position ergonomique**
(meilleure visualisation, prévention des TMS)
- **Protection totale des Rx**
- **Courbe d'apprentissage rapide** (simplicité/sécurité)
- **Guide verrouillé**
- **Conversion manuelle rapide** et intuitive (R-one)



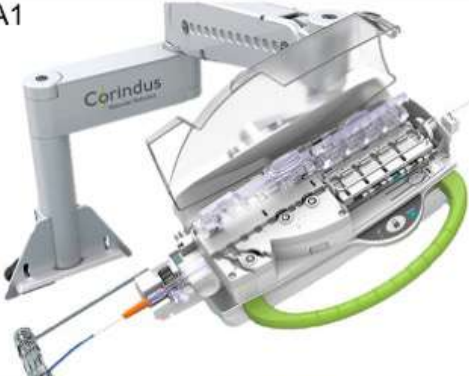





Patients

- **Précision** (manipulation guide, positionnement du stent)
- **Diminution de l'exposition** aux Rx
- **Diminution du contraste**
- **Moins de fatigue** pour l'opérateur/meilleur résultat ?



Centres

- **Innovation**
- **Attractivité**
(opérateur/patient)
- **Coopération Médecin/2nd opérateur: IDE**
- **Programmes de formation**

Corindus CorPath 200	Corindus CorPath GRX	R-One
<p>A1</p>  <p>The image shows the Corindus CorPath 200 robotic system, which includes a robotic arm with the Corindus logo, a transparent catheter housing, and a green handle.</p>	<p>B1</p>  <p>The image shows the Corindus CorPath GRX robotic system, featuring a robotic arm, a transparent catheter housing, and a green handle, similar to the CorPath 200 but with a different handle design.</p>	<p>C1</p>  <p>The image shows the R-One robotic system, which consists of a light blue transparent catheter housing mounted on a white base with a black handle labeled 'Roboath'. The base has a red emergency stop button.</p>
<p>A2</p>  <p>The image shows a person's hands operating the control console for the Corindus CorPath 200. The console features a large touchscreen displaying a graphical interface with various icons and a joystick.</p>	<p>B2</p>  <p>The image shows the control console for the Corindus CorPath GRX. It has a large touchscreen displaying a detailed graphical interface with various data points and controls, and a prominent green joystick.</p>	<p>C2</p>  <p>The image shows the control console for the R-One system. It features a large touchscreen with a simplified graphical interface and two black joysticks for manual control.</p>



Attaching single-use cassette



Connecting guide catheter



Device loading in the cassette



Operator performs PCI from the control station

Study	Study Design	R-PCI system	Patients	Primary Endpoints	Groups	Technical success	Clinical success
Beyar, et al. 2006	Pilot Clinical Study	Remote Navigation System (RNS)	18	To evaluate safety and feasibility of a novel RNS		94% Guide wire navigation 83% Overall procedure	100%
Granada, et al. 2011	Single-arm, open-label, prospective	CorePath 200™	8	Device clinical success (< 30% residual stenosis) without in-hospital MACE		97.90% The robotic-system completed 47 of 48 planned steps	100%
PRECISE 2013	Prospective, single-arm, multicenter, open-label, non-randomized study	CorePath 200™	164	Clinical procedural success device technical success		98.80% Conversion to M-PCI (n = 2)	97.9% Periprocedural MI (n = 4)
PRECISION Registry	Registry	CorePath 200™	273, 344 lesions			93.70%	85.70%
CORA-PCI-2017	Non-randomized, single-center, comparison study	CorePath 200™	315	Clinical success (successful PCI without MACE)	108 R-PCI, 226 M-PCI	91.7% R-PCI Manual assistance (11.1%) Manual conversion (7.4%)	91.1% R-PCI 91.1% M-PCI
Smitson et al. 2018	vProspective, single-arm, multicenter, open-label, non-randomized study	CorPath GRX	40	Clinical procedural success (<30% residual stenosis without in-hospital MACE) Device technical success (robotic procedural success without the need for unplanned manual conversion)		90% Unable to advance overlapping stent (n = 1) Unable to cross lesion with guide wire (n = 1) Unable to cross lesion with balloon (n = 1)	97.50%
Hirai et al. 2020	Retrospective	CorPath GRX	95	Procedure time Cockpit time	46 Manual CTO-PCI 49 Robotic CTO-PCI	No difference in procedure time or MACE Higher cockpit time in robotic PCI	